



## USER MANUAL

EVALUATION BOARD/KIT FOR RADIO MODULE TRITON

2603011021000 / 2603011121000

VERSION 2.4

OCTOBER 8, 2024

WURTH ELEKTRONIK MORE THAN YOU EXPECT

## **MUST READ**

### Check for firmware updates

Before using the product, make sure you use the most recent firmware version, data sheet, and user manual. This is especially important for Wireless Connectivity products that were not purchased directly from Würth Elektronik eiSos. A firmware update on these respective products may be required.

We strongly recommend including the possibility of a firmware update in the customer system design.



## **Revision history**

| Manual version | HW<br>version | Notes  | Date          |
|----------------|---------------|--|---------------|
| 1.0-1.4        | 2.1           | <ul> <li>Initial version</li> </ul>                    | June 2017     |
| 2.0            | 2.1           | <ul> <li>New corporate design and structure</li> </ul> | December 2018 |
| 2.1            | 2.1           | • Added chapter Regulatory compliance information      | February 2019 |
| 2.2            | 2.1           | <ul> <li>Added marketing name</li> </ul>               | March 2019    |
| 2.3            | 2.1           | <ul> <li>New corporate design</li> </ul>               | May 2023      |
| 2.4            | 2.1           | • Added chapter Supported UART baud rates              | October 2024  |



## Abbreviations

| Abbreviation | Name   | Description   |
|--------------|--|---|
| BDM          | Business<br>Development<br>Engineer                  | Support and sales contact person responsible for limited sales area                                       |
| HIGH         | High signal level                                    |   |
| LOW          | Low signal level                                     |   |
| RF           | Radio frequency                                      | Describes everything relating to the wireless transmission.   |
| UART         | Universal<br>Asynchronous<br>Receiver<br>Transmitter | Universal Asynchronous Receiver Transmitter allows communicating with the module of a specific interface. |
| VDD          | Supply voltage                                       |   |



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## 1 Supported radio modules

The EV-Board described in this manual can be used to evaluate the following products:

| Order code    | Former order code | Marketing Name |
|---------------|-------------------|----------------|
| 260301102100x | AMB2220(TR)       | Triton         |
| 260301112100x | AMB2220-1(TR)     | Triton         |

| Order code    | Description   |
|---------------|---|
| 260301102100x | 2.4 GHz proprietary radio module with integrated chip antenna |
| 260301112100x | 2.4 GHz proprietary radio module with antenna pad             |

Table 1: Compatibility



Figure 1: Product image



## 2 Functional description

The EV-Board offers the user the possibility to develop hard- and software for the compatible radio module. It can be connected to an USB port of a PC.

For the connection to a microcontroller system the development board is equipped with a multipin connector which is connected to all pins of the RF module. Jumpers allow the module to be disconnected from components which are not required such as the USB interface.

Feel free to check our YouTube channel for video tutorials, hands-ons and webinars related to our products:

www.youtube.com/user/WuerthElektronik/videos

## 2.1 Taking into operation

To run the EV-Board place the jumpers and switches on their default position (see section 3.2). The corresponding FTDI driver package (*http://www.ftdichip.com/Drivers/VCP.htm*) has to be installed on your PC. Please make sure you keep that driver up-to-date.

The next step is to connect the Mini-USB (CON2) of the EV-Board to the PC using an USBcable. In that way a COM port can be detected and installed on your PC. Check the device manager to acquire the COM port name of the EV-Board. a typical name is "COM12" in Windows systems or in Linux system /dev/ttyUSB0

A terminal program (like *hterm*) has to be run and the corresponding COM port has to be opened using the default settings of the mounted radio module (e.g. 9600 Baud with 8 data bits, no parity, 1 stop bit).

After the module is powered through the USB jack, the reset button should be pressed to ensure a clean start-up of the module.

Please refer to the module user manual to get the detailed quick start instructions.

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## 3 Development board

## 3.1 Block diagram

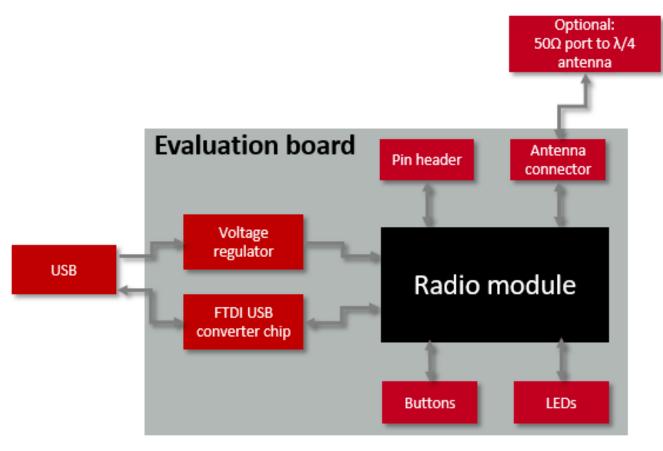


Figure 2: Block diagram



## 3.2 Jumpers

The following figure shows the default positioning (marked in red) of all jumpers on the EV-Board. This section also contains the details to any jumper connection that is supported by the EV-Board.

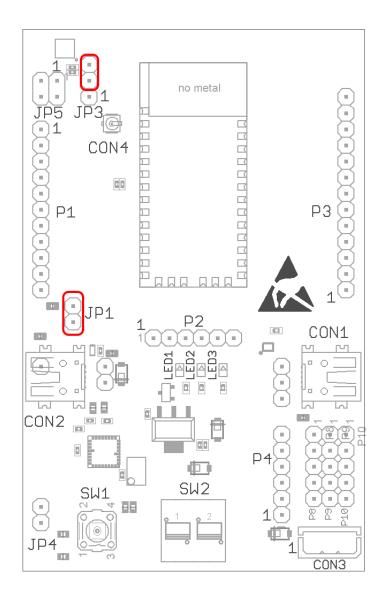


Figure 3: Jumpers, defaults

| JP1 | Jumper placed<br>(default) | Description                                   |
|-----|----------------------------|---|
| 1,2 | Set 1-2                    | Measuring bridge current supply of the module |

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| JP3   | Jumper placed<br>(default) | Description   |
|-------|----------------------------|---|
| 1,2,3 | Set 2-3                    | <ul><li>1-2 enable the accelerometer</li><li>2-3 turn off the accelerometer</li></ul> |

| JP4 | Jumper placed<br>(default) | Description         |
|-----|----------------------------|---------------------|
| 1-2 | Not Set                    | BOOT0 pin of module |

| JP5 | Jumper placed<br>(default) | Description   |
|-----|----------------------------|---|
| 1,2 | Not Set                    | Connection of interrupt pin 1 of accelerometer sensor |
| 3,4 | Not Set                    | Connection of interrupt pin 2 of accelerometer sensor |

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## 3.3 Connectors and pin headers

This section explains all connectors and pin headers on the EV-Board.



All reserved pins shall be handled/terminated as described in the module specific manual.

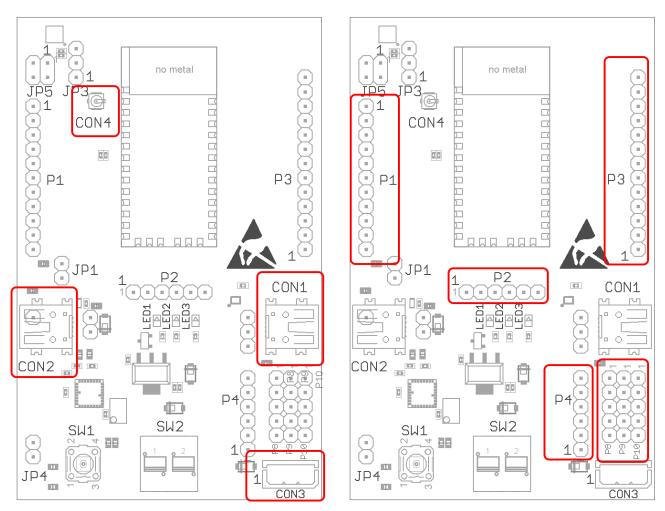


Figure 4: Connectors

Figure 5: Pin headers

| CON1 | Function | Description  |
|------|----------|--|
| -    | USB1     | USB connector to STM32 USB, not supported by standard firmware, do not connect |

| CON2 | Function | Description                                   |
|------|----------|---|
| -    | USB2     | USB connector to module UART and power supply |

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| CON3 | Function | Description                        |
|------|----------|------------------------------------|
| -    | Battery  | Connector for battery-pack, 3 Volt |

| CON4 | Function | Description  |
|------|----------|--|
| -    | Antenna  | U.FL socket connection to 50 $\Omega$ radio path of the module, only active for Modules with RF-pad (i.e. without internal antenna). |

| P1   | Description                  |
|------|------------------------------|
| 1-11 | Direct access to module pins |

| P2  | Description                  |
|-----|------------------------------|
| 1-6 | Direct access to module pins |

| P3   | Description                  |
|------|------------------------------|
| 1-11 | Direct access to module pins |

| P8  | Function | Description |
|-----|----------|-------------|
| 1-5 | VDD      | Power       |

| P9  | Function | Description   |
|-----|----------|---------------|
| 1-5 | n.c.     | not connected |

| P10 | Function | Description |
|-----|----------|-------------|
| 1-5 | GND      | Ground      |



## 3.4 LEDs

This section explains all LEDs on the EV-Board.

|      | Function  | Description                              |
|------|-----------|--|
| LED1 | Power LED | Lights up if EV-Board power is supplied  |
| LED2 | TX LED    | Lights up if module transmits radio data |
| LED3 | RX LED    | Lights up if module receives radio data  |

## 3.5 Switch

This section explains all switches on the EV-Board. The default switch positions are indicated in red.

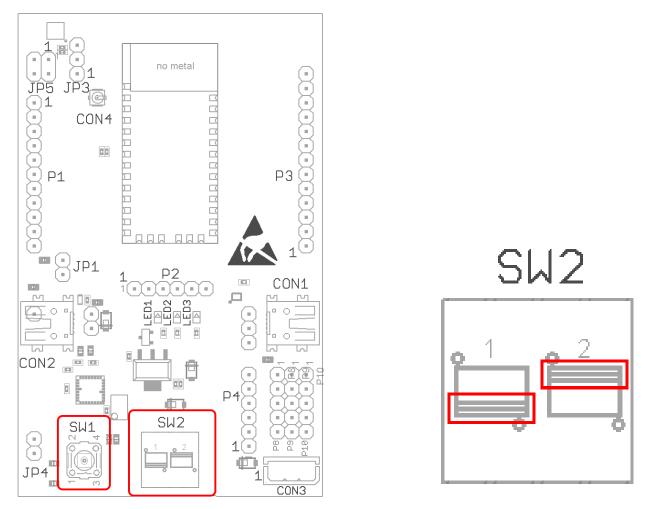


Figure 6: Switch SW2 default position and SW1 Reset button





| SW2 | Function | Description           |  |
|-----|----------|-----------------------|--|
| 1   | SW2.1    | WAKE_UP pin of module |  |
| 2   | SW2.2    | Boot1 pin of module   |  |

Table 2: Switch SW2

## 3.6 Reset button

Every module provides a */RESET pin* that is connected to this SW1 button so the module can be (re)started properly. A pressed button connects the */RESET* to LOW logic level and holds the module in reset until it is released. Most modules provide an internal pull-up resistor. Please refer to the module specific manual for detailed information upon the module's */RESET* pin and recommended start-up sequences for the module.

| SW1 | Function | Description                    |  |
|-----|----------|--------------------------------|--|
|     | SW1      | Button to /RESET pin of module |  |

Table 3: Button SW1

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## 4 Function blocks

## 4.1 Power supply

There are several possibilities to supply the EV-Board and the module with power.

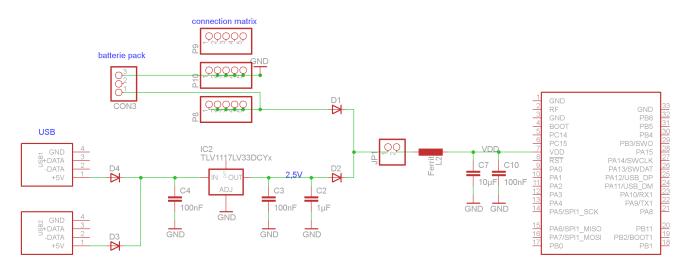


Figure 7: Power supply schematic

The different power terminals are all connected with diodes to protect them from each other, therefore no selection by additional jumpers is necessary. Nevertheless the customer shall apply only one USB connector to the EV-Board. An external power supply through P8 and P10 shall not be used when a battery pack is connected to CON3.

## 4.1.1 Power supply over USB: CON2

Connecting the USB interface CON2 supplies the board through the low dropout voltage (LDO) regulator. The module is supplied by approximately 2.5 V (2.5 V LDO minus forward voltage of the diode of approx. 0.2V).

## 4.1.2 Power supply over battery pack 3V: CON3

Connecting the battery pack supplies the module with the voltage delivered from the pack minus approx. 0.2V forward voltage of the diode.

## 4.1.3 External supply: P8, P10

Two 2.54 mm headers are available for connection from an external source to VCC and GND. Make sure you provide a stable current in the range of 2.5 to 3.6 Volt to this pins. It is suitable to supply the development board and associated electronics from one power supply, as well as to test the system with different voltage levels.

### 4.2 Current measurement

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JP1 can be used to measure the power consumption of the module. By default a bridge is set on JP1 to close the circuit. Remove the bridge and connect a current meter in place of the jumper to measure the power consumption of the module. If the meter is not attached and the bridge is not set, the module will not receive a supply voltage and is not active.



When the EV-Board is supplied with VCC the power LED is active even if JP1 is left open. This is to avoid measuring the current through the LED during module current measurements.



Measuring module currents, especially in low power mode, SW2.2 has to be turned to position "up" (default position) and SW2.1 has to be left in position "down" (default position), else additional leakage current because of the pull resistors will be observed. All other module pins shall be terminated as indicated in the module specific manuals.

## 4.3 Host interface: USB, CON2

The UART of the module is available on CON2 as USB. The parallel usage of the USB on CON2 and standalone UART TX1 & RX1 on P3 is not possible as these two share the same module pins. Using P3 for direct UART connection requires the CON2 to be not connected to USB as the electronic switch will then disable the connection of TX and RX module to the FTDI converter IC to prevent signal disturbance because of the converter IC.

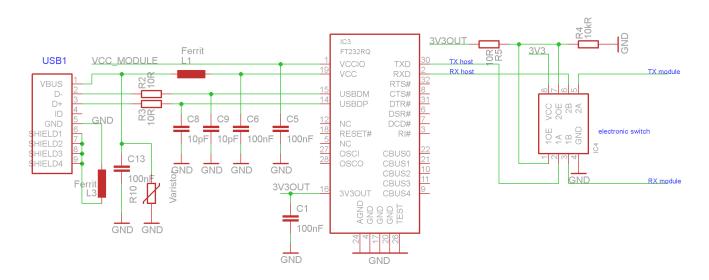


Figure 8: UART to USB converter: FT232R



### 4.3.1 Supported UART baud rates

In order to establish a stable UART communication between the FTDI USB to UART converter chipset and the radio module's chipset, the difference between the baud rates of each entity must not exceed the respective immunity level. Both devices use an internal clock to generate the configured UART baud rate. Due to the fixed clock frequency, only specific baud rates can be run without frequency error.

To figure out which baud rates of the radio module can be evaluated using the mounted FTDI chipset (FT232R or FT231X), it is important to know the real baud rate B with its introduced error. To get them, the FTDI's clock of 3000 kHz must be divided by the respective prescaler P:

$$B = \frac{3000}{P} \text{ [kBaud]}$$

The supported prescalers *P* can be chosen as:

$$P \in \{1, 1.5\}$$
 or  $P = 2 + (N \cdot 0.125)$  with  $N \in \{0, 1, 2, 3, 4, \ldots\}$ 

When a baud rate is configured in the FTDI chip, the prescaler is chosen that meets the closest baud rate. In that case, the real baud rate differs from the configured one, introducing a UART clock error, which may lead to UART communication issues.

**Example:** In case the desired baud rate  $B_{desired} = 1250$  kBaud, the desired prescaler is  $P_{desired} = \frac{3000}{1250} = 2.4$ . The closest prescaler P is determined by  $P = 2 + (N \cdot 0.125) = 2.375$  with N = 3. This results in a real baud rate  $B = \frac{3000}{2.375} = 1263$  kBaud, which introduces an error of  $\frac{B-B_{desired}}{B_{desired}} = 1.04$  % with respect to the desired baud rate.

| Desired baud rate<br>[kBaud] | Closest<br>prescaler P | Real baud rate <i>B</i> [kBaud] | Error<br>[%] |
|------------------------------|------------------------|---------------------------------|--------------|
| 3000                         | 1                      | 3000                            | 0            |
| 2500                         | 1.5                    | 2000                            | -20          |
| 2000                         | 1.5                    | 2000                            | 0            |
| 1500                         | 2                      | 1500                            | 0            |
| 1250                         | 2.375                  | 1263                            | 1.04         |
| 1411.764706                  | 2.125                  | 1411.764706                     | 0            |
| :                            | :                      | ÷                               | :            |
| 1000                         | 3                      | 1000                            | 0            |
| 921.6                        | 3.25                   | 923.0769231                     | 0.16         |
| :                            | :                      | :                               | :            |
| 230.4                        | 13                     | 230.7692308                     | 0.16         |
| :                            | :                      | :                               | :            |
| 115.2                        | 26                     | 115.3846154                     | 0.15         |
| :                            | :                      | ÷                               | :            |
| 38.4                         | 78.125                 | 38.4                            | 0            |
| :                            | :                      | :                               | :            |
| 19.2                         | 156.25                 | 19.2                            | 0            |

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|-------------------------|-----------|
|-------------------------|-----------|

|     |       |     | : |
|-----|-------|-----|---|
| 9.6 | 312.5 | 9.6 | 0 |
|     | :     |     | : |

## 4.4 Host interface: UART P3

The UART of the module is available on P3.11 and P3.12. The parallel usage of the USB on CON2 and standalone UART TX1 & RX1 on P3 is not possible as these two share the same module pins. Using P3 for direct UART connection requires the CON2 not to be connected to USB as the electronic switch will then disable the connection of TX and RX module to the FTDI converter IC to prevent signal disturbance because of the converter IC.

Beware of IO level incompatibility. The host must obey the values stated in the module's manual. Especially the IO level restrictions must be implemented by a host system (i.e. using a level shifter to use the allowed IO levels).

### 4.5 UART bootloader vs. application

The levels at the pins *Boot0* and *Boot1* decide, right after a module reset, if the application or the UART bootloader of the module is started.

To start the application safely and measure a correct current the default switch and jumper settings of the EV-Board are sufficient. See figures 3 and 6.

To safely start the module's bootloader JP4 must be mounted while SW2.2 is in position "up". Then a reset of the module using the reset button SW1 must be performed to start the module in UART bootloader mode.

The UART bootloader mode can be left by reverting the Jumpers and switches back to defaults and perform another reset of the module.

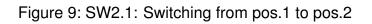
### 4.6 Wake-up function, switch SW2.1

Switch SW2.1 is connected to module pin 10, which is used as wake-up in the standard firmware. In default case the SW2.1 is in position "down".

If the module is in sleep mode, the SW2.1 can be used as *WAKE-UP* pin. To trigger the wake up a falling edge has to be applied at the *WAKE-UP* pin of the module, which means to switch SW2.1 from position "down" to position "up". When the module is no longer in sleep mode, SW2.1 should be switched back to default position "down" to prevent leakage current.







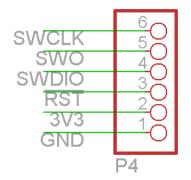


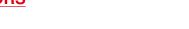
Figure 10: P4 SWD connector

## 4.7 Programming interface

The EV-Board provides a 1\*6 pin connector in RM2.54 to connect to a SWD flash adapter used for development. Please take care of the correct mounting of the flash adapter. Depending on your Flasher an additional adapter may be required.

The recommended flash adapter is one of the "Segger J-Link" family with SWD support or an ST-Link V2 adapter with SWD support.

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## 4.8 Full schematic

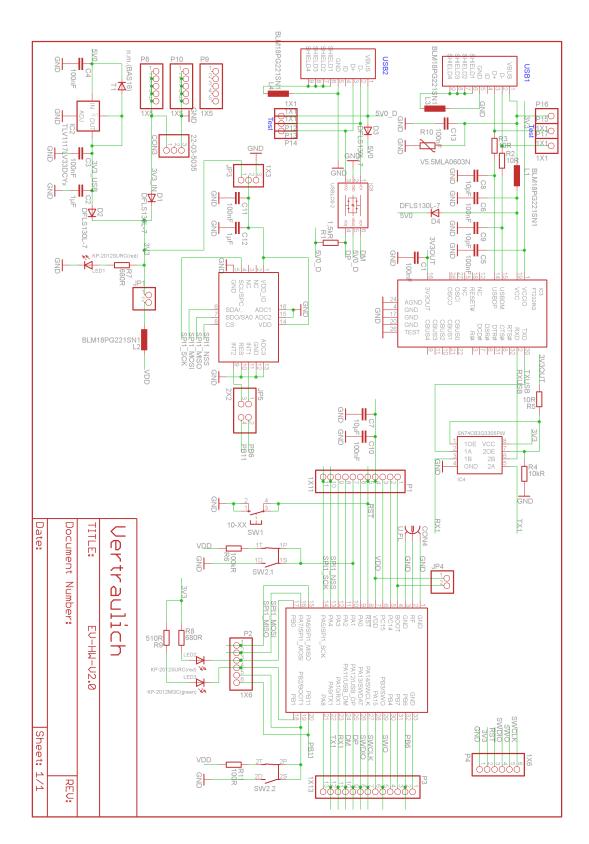
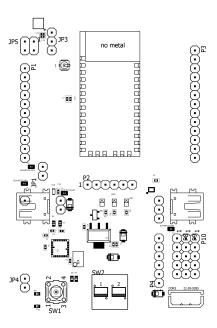


Figure 11: Wiring diagram

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## 4.9 Full layout





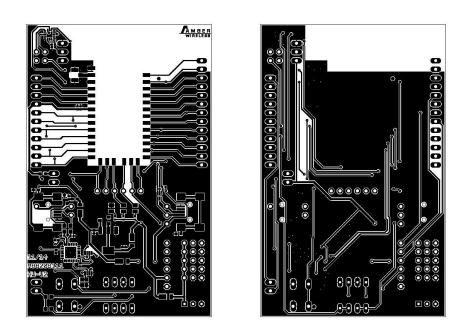


Figure 13: Top and Bottom Layer



## 4.10 Sensor: SPI accelerometer

JP3 serves to either supply the accelerometer from the common power supply, or to deactivate the accelerometer (triple axis, type: STM LIS3DH) by holding its supply pin to GND level. To be able to use the accelerometer a customer specific module firmware is required.



The accelerometer is not used in AMB2220/Triton standard firmware, thus JP3 should be placed to connect 2-3 and JP5 connections 1-2 and 3-4 shall be left open.

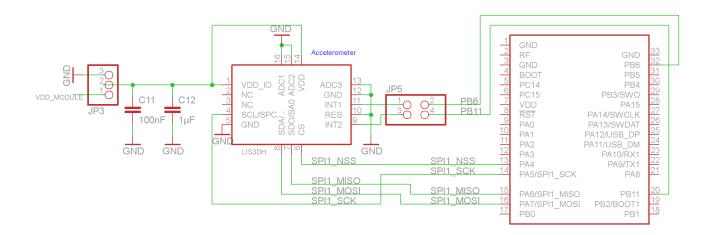


Figure 14: Connection of SPI accelerometer to module



## 5 Marking

## 5.1 Lot number

The 15 digit lot number is printed in numerical digits as well as in form of a machine readable bar code. It is divided into 5 blocks as shown in the following picture and can be translated according to the following table.

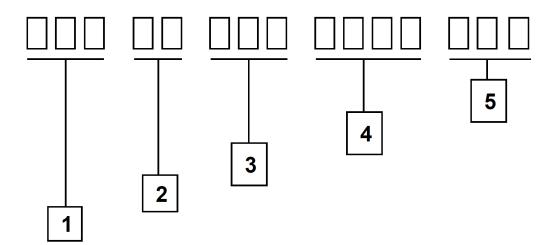


Figure 15: Lot number structure

| Block | Information                                | Example(s)                   |
|-------|--|------------------------------|
| 1     | eiSos internal, 3 digits                   | 438                          |
| 2     | eiSos internal, 2 digits                   | 01                           |
| 3     | Radio module hardware version,<br>3 digits | V2.4 = 024, V12.2 = 122      |
| 4     | Date code, 4 digits                        | 1703 = week 03 in year 2017, |
|       |  | 1816 = week 16 in year 2018  |
| 5     | Radio module firmware version,<br>3 digits | V3.2 = 302, V5.13 = 513      |

Table 5: Lot number details

As the user can perform a firmware update the printed lot number only shows the factory delivery state. The currently installed firmware can be requested from the module using the corresponding product specific command. The firmware version as well as the hardware version are restricted to show only major and minor version not the patch identifier.

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## 6 Regulatory compliance information

Pursuant to Article 1 (2.) of the EU directive 2014/53/EU, Article 1 (2.) the directive does not apply to equipment listed in Annex I (4.): custom-built EV-Kits destined for professionals to be used solely at research and development facilities for such purposes.

## 6.1 Exemption clause

Relevant regulation requirements are subject to change. Würth Elektronik eiSos does not guarantee the accuracy of the before mentioned information. Directives, technical standards, procedural descriptions and the like may be interpreted differently by the national authorities. Equally, the national laws and restrictions may vary with the country. In case of doubt or uncertainty, we recommend that you consult with the authorities or official certification organizations of the relevant countries. Würth Elektronik eiSos is exempt from any responsibilities or liabilities related to regulatory compliance.

Notwithstanding the above, Würth Elektronik eiSos makes no representations and warranties of any kind related to their accuracy, correctness, completeness and/or usability for customer applications. No responsibility is assumed for inaccuracies or incompleteness.



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### Customer responsibility related to specific, in particular safety-relevant applications

It has to be clearly pointed out that the possibility of a malfunction of electronic components or failure before the end of the usual lifetime cannot be completely eliminated in the current state of the art, even if the products are operated within the range of the specifications. The same statement is valid for all software source code and firmware parts contained in or used with or for products in the wireless connectivity and sensor product range of Würth Elektronik eiSos GmbH & Co. KG. In certain customer applications requiring a high level of safety and especially in customer applications in which the malfunction or failure of an electronic component could endanger human life or health, it must be ensured by most advanced technological aid of suitable design of the customer application that no injury or damage is caused to third parties in the event of malfunction or failure of an electronic component.

### Best care and attention

Any product-specific data sheets, manuals, application notes, PCNs, warnings and cautions must be strictly observed in the most recent versions and matching to the products revisions. These documents can be downloaded from the product specific sections on the wireless connectivity and sensors homepage.

### Customer support for product specifications

Some products within the product range may contain substances, which are subject to restrictions in certain jurisdictions in order to serve specific technical requirements. Necessary information is available on request. In this case, the Business Development Engineer (BDM) or the internal sales person in charge should be contacted who will be happy to support in this matter.

### Product improvements

Due to constant product improvement, product specifications may change from time to time. As a standard reporting procedure of the Product Change Notification (PCN) according to the JEDEC-Standard, we inform about major changes. In case of further queries regarding the PCN, the Business Development Engineer (BDM), the internal sales person or the technical support team in charge should be contacted. The basic responsibility of the customer as per section 7 and 7 remains unaffected.

All software like "wireless connectivity SDK", "Sensor SDK" or other source codes as well as all PC software tools are not subject to the Product Change Notification information process.

### Product life cycle

Due to technical progress and economical evaluation, we also reserve the right to discontinue production and delivery of products. As a standard reporting procedure of the Product Termination Notification (PTN) according to the JEDEC-Standard we will inform at an early stage about inevitable product discontinuance. According to this, we cannot ensure that all products within our product range will always be available. Therefore, it needs to be verified with the Business Development Engineer (BDM) or the internal sales person in charge about the current product availability expectancy before or when the product for application design-in disposal is considered. The approach named above does not apply in the case of individual agreements deviating from the foregoing for customer-specific products. The approach named above does not apply in the case of EV-Boards. EV-Boards may be changed without any notification.

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### General warnings

Do not touch the EVB when it is live, and allow charged components, such as capacitors, to discharge completely before handling the EVB. Depending on the individual application, high voltages can occur on the EVB and some components can reach temperatures above 50 °C. Even after disconnecting the EVB from the power source, these conditions remain for a significant time. Please ensure that the appropriate safety precautions are taken when installing and operating this EVB, as one of the following may occur if you handle or use this EVB without observing the relevant safety precautions: - Death - Serious injury - Electric shock - Electric burns - Severe heat burns -

When using the EVB, you undertake to read the instructions for use in full together with the relevant information supplied and/or available on the homepage *www.we-online.de/wcs-manuals* before putting this EVB into operation. The following points have to be observed in particular: • Do not touch the EVB while it is live.

- The EVB must be fully assembled and all devices to be tested must be connected before voltage is applied to the EVB.
- The EVB should never be left unattended during operation.
- Capacitors must be completely discharged. The capacitors must be actively discharged using a suitable resistor.

### Protection against static electricity

Use the unpackaged product only in ESD protected areas. Wear the ESD personal protective equipment prescribed for these areas. Ground all conductive components, including personnel, as prescribed in ESD protected areas. Ensure that the product is only used by trained personnel.

#### Purpose and use

The EVB is not a finished product and is not intended for general use by the consumer. The EVB is intended exclusively for use in the evaluation of WE components in the lab or in development environments by highly qualified technicians or engineers, familiar with the risks involved in handling electrical or mechanical components, systems and subsystems. The use of the EVB is your full and independent responsibility. The EVB is expressly not intended to be installed in a terminal device or to be part of a terminal device in whole or in part. WE reserves the right, at its own discretion, to make corrections, improvements, adjustments or other changes to the EVB or to discontinue the EVB. The EVB is not intended for use in devices and applications for which a higher safety and reliability standard is prescribed. It is also not approved for use in safety-relevant applications or where personal injury or fatal consequences must be expected in the event of failure.

#### Operation of the EVB

The EVB may only be operated within the specifications and environmental parameters recommended by WE, as described in the instructions for use. Exceeding the specified parameters (including, but not limited to, input and output voltage, current, power, and ambient conditions) may result in damage to property. If you have questions about these electrical parameters, please contact WE at (regulatory-compliance@we-online.com) prior to connecting peripheral electronics (including the input voltage and intended loads). Any load outside a certain power range may lead to negative consequences, including, but not limited to, unintended or inaccurate evaluations or possibly permanent damage to the EVB or the electronics connected to it. Please ensure that the appropriate safety precautions are taken when working with the EVB, as serious injuries, including severe or even fatal injuries from electric shock or electric burns, may occur if you do not follow the appropriate safety precautions. Under no circumstances should the EVB be touched while live. When the EVB is connected to a power source, some of its components are electrically charged and/or have temperatures above 50 °C. This condition also applies for a short time after disconnecting from the supply voltage until the capacitors are completely discharged and hot components have cooled down. These components include connectors, linear regulators, switching transistors, heat sinks, resistors, diodes, inductors and other components, which can be identified from the documentation in the instructions for use. As with all electronic lab work, only qualified persons with knowledge of electronic performance evaluation, measurement and diagnostic tools, should use the EVB.

#### Hazards and warnings

Before putting the EVB into operation, please read the instructions for use and especially the various hazards and warnings described therein. The instructions for use contain important safety information on voltages and temperatures. You take full responsibility and liability for the proper and safe handling of the EVB. You agree to comply with all safety requirements, rules and regulations related to the use of the EVB. You also take full responsibility for: (1) establishing safeguards to ensure that the use of the EVB does not cause damage to property, personal injury or death, even if the EVB does not function as described, intended or expected, (2) the test setup in which the EVB is integrated, all safety requirements, rules and regulations and also that no damage to property, personal injury or other hazardous situation occurs even if the EVB fails, and (3) ensuring the safety of all activities performed by you or your employees when using the EVB. In particular, this means that the technical rules VDE [German Electrical Engineering, Electronic and Information Technology Association] 0105-100 and BGI [German trade association information] 891 (or corresponding applicable safety regulations outside Germany) for the operation of electrical test setups must be observed, the test area is protected against unauthorized access or accidental touching, current limitations, and emergency stop mechanisms are functional and test setups are never operated unattended. If you have any questions about the safe use of the EVB, please contact WE at *regulatory-compliance@we-online.com* for more information.

### Your responsibility with regard to the applicable laws

• You are responsible for being sufficiently informed about and complying with all international, national, state and local applicable laws, rules and regulations that apply to the handling or use of the EVB by you or your employees.

• The EVB generates, uses and radiates radio frequency energy, but has not been tested for conformity with the limits applicable to the product category, which are applicable according to the European Union regulations for protection against radio frequency interference. Operation of the EVB may cause interference with radio communication. In this case, the costs incurred for necessary measures to remedy the interference are to be borne by the user.

As the EVB is not a finished product, it may not comply with applicable regulatory, safety or certification standards that are normally as-

### Evaluation board/kit user manual



sociated with other products, such as Directive 2011/65/EC of the European Parliament and of the Council of 8 June 2011 on the restriction of the use of hazardous substances and Directive 2002/96/EC on waste electrical and electronic equipment (WEEE). You take full responsibility for compliance with such standards that apply to the EVB. You also take responsibility for the proper disposal of the components and materials of the EVB.

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WE ensures that the EVB meets the specifications given in the instructions for use (within the deviations stated therein) for a period of 12 months from the date of purchase and functions in accordance with the instructions for use. On the basis of the underlying statutory provisions, WE shall rectify defects or offer free replacement of the EVB to which damage occurs that is evidently attributable to a defect for which WE is responsible and is at fault. A warranty claim is subject to the user having complied with the statutory duties of inspection and notification of defects and that the EVB has been received by WE no later than ten (10) days after expiry of the warranty period. This warranty is not transferable to others. This warranty does not apply to defects or impairments in performance resulting from incorrect use, use contrary to WE's instructions, improper installation, improper operation or misuse. WE accepts no liability whatsoever for the failure of equipment or other items not manufactured by or for WE, including, but not limited to, equipment or items to which the EVB is attached or for which the EVB is used. WE DOES NOT GRANT ANY WARRANTIES OR ASSURANCES WHATSOEVER, EXPRESS OR IMPLIED, WITH RESPECT TO THE EVB, INCLUDING, BUT NOT LIMITED TO, ANY IMPLIED WARRANTIES OF MARKETABILITY OR SUITABILITY FOR A PARTICULAR PURPOSE.

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